

## Fibonacci Heap

Thanks to Sartaj Sahni for the original version of the slides

## Priority Queues

	Heaps				
	Binary	Binary	Binary	Binary	Binary
make-heap	1	1	1	1	1
insert	1	log N	log N	1	1
find-min	N	1	log N	1	1
delete-min	N	log N	log N	log N	log N
union	1	N	log N	1	1
decrease-key	1	log N	log N	1	1
delete	N	log N	log N	log N	log N
is-empty	1	1	1	1	1

Dijkstra/Prim  
 1 make-heap  
 |V| insert  
 |V| delete-min  
 |E| decrease-key

$O(|V|^2)$        $O(|E| \log |V|)$        $O(|E| + |V| \log |V|)$

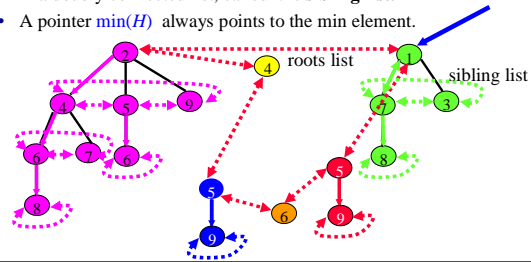
## Fibonacci heaps



- Similar to binomial heaps, consists of a collection of trees, each arranged in a heap-order (each node is smaller than each of its children)
- Unlike binomial heaps, can have many trees of the same cardinality, and a tree does not have to have exactly  $2^i$  nodes.
- Main idea – **laziness** is welcomed. Try to postpone doing the hard work, until no other solution works.

## General Structure

- Very similar to Binomial heaps
- Main structure: A collection of trees, each in a heap-order.
- All roots are stored in a doubly connected list, called the **roots-list**.
- Every node points to one of its childrens. All the children are stored in a doubly connected list, called the **sibling-list**.
- A pointer  $\text{min}(H)$  always points to the min element.



## Node Structure



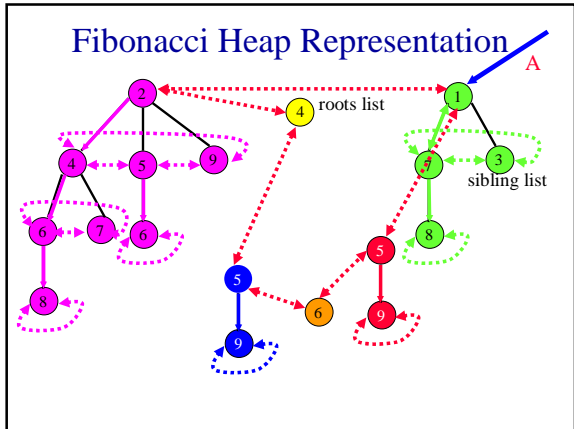
- Very similar to Binomial heaps
- Each node  $v$  stores its
  - degree,
  - a pointer to its parent,
  - a pointer to a child,
  - data,
  - Pointers to left and right sibling used for circular doubly linked list of siblings, called the **sibling list**.

More – in next slide

## Node Structure



- Each node  $v$  stores a flag **ChildCut** (not existing in binomial heaps)
  - **True** only if
    - $v$  is not a root, and
    - $v$  has lost a single child since became a child of its current parent.
  - We say that  $v$  is **marked** in this case.
- Will see: *Extract\_Min* is the only operation that makes one node a child of another, and then flag might change.
  - Flag is undefined for a root node (not used)



### Potential Function

Some nodes would be marked (to be explained later)  
 We use the potential functions for the heap  $H$   
 $\Phi(H) = t(H) + 2 m(H)$

Where  $t(H)$  is the number of trees in  $H$   
 And  $m(H)$  is the number of marked nodes in  $H$ .

### Insert( $x$ )

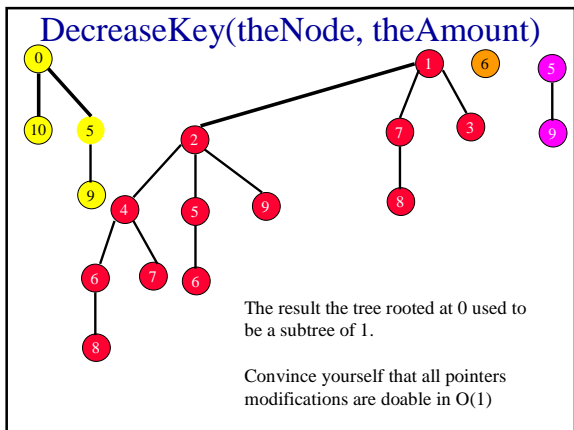
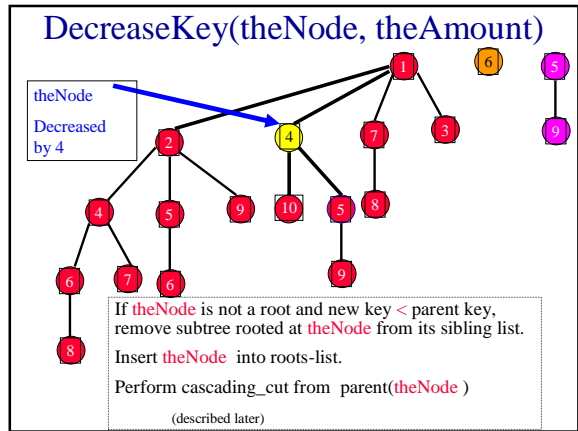
Create a new tree consisting of a single node  $v$  whose key is  $x$ .  
 Add  $v$  to the roots list. (always unmarked)

Actual time  $w_i$  needed for the operation is  $1$ .

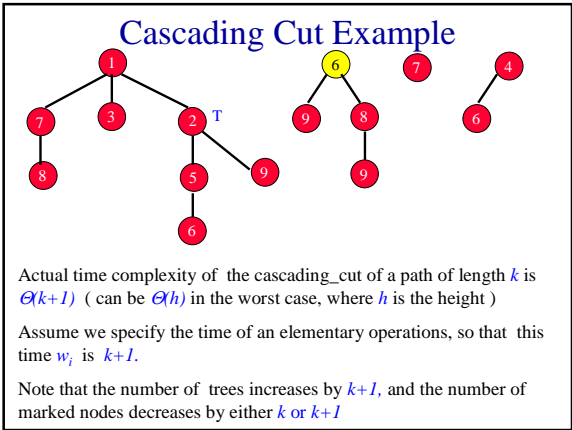
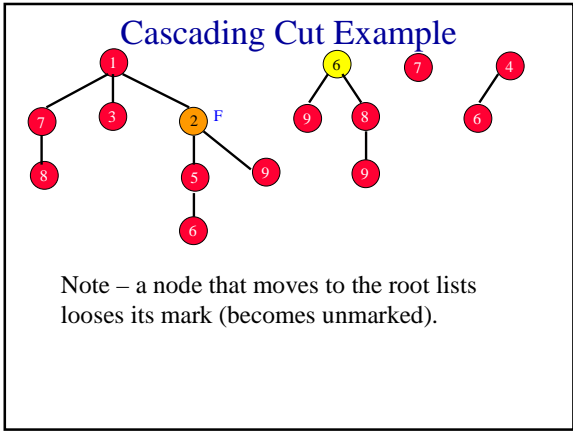
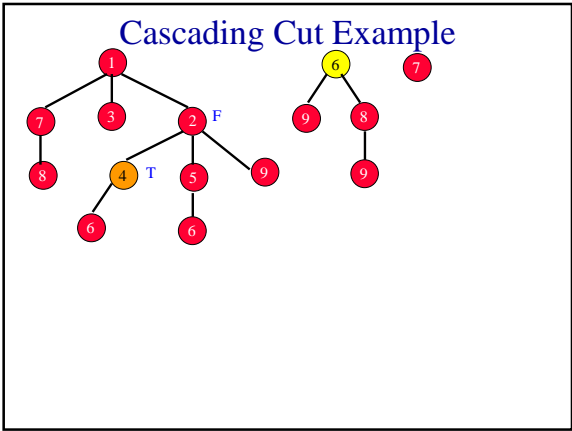
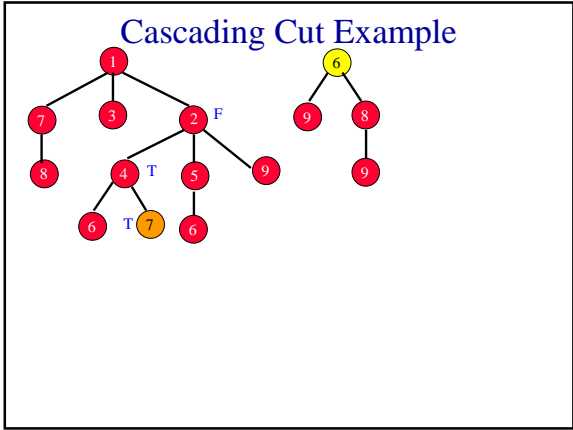
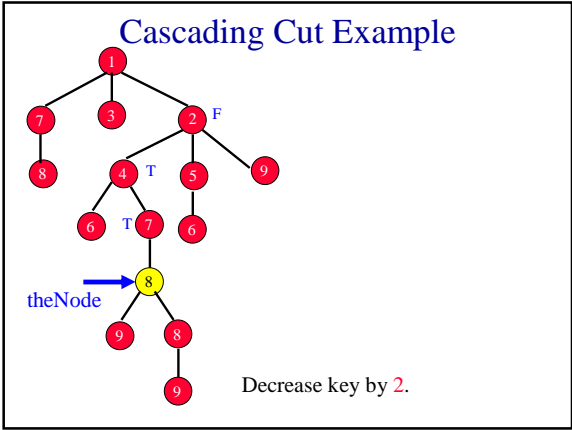
Number of trees increased by  $1$ .

Changes in potential function  
 $\Phi(H') - \Phi(H) = \Delta\Phi(H) = t(H') + 2 m(H') - t(H) - 2 m(H) = 1$

So the amortized work  $a_i = w_i + \Delta\Phi(H) = 2$



- ### Cascading Cut
- When **theNode** is cut out of its sibling list in a decrease key operation, follow path from parent of **theNode** upward toward the root.
  - Encountered nodes (other than root) with **ChildCut = true** are cut from their sibling lists and inserted into roots-list.
  - Stop at first node with **ChildCut = false**.
  - For this node, set **ChildCut = true**. (since it just lost exactly one child)
- In other words, if a node lost two children since it became a child, it must move itself from the parent to the roots-list.*



### Amortized time

Note that the number of marked nodes decreases by  $k$  or  $k+1$ , and the number of trees increased by  $k+1$ .

Let  $H'$  to be  $H$  denote the heap before and after the  $\mathcal{L}$ Decrease\_min operation, then  $t(H') = t(H) + k + 1$  and  $m(H') = m(H) - k$

The change in the potential function is (denoting  $H'$  to be  $H$  after the Decrease\_min ) is

$$\Phi(H') - \Phi(H) = (t(H') + 2m(H')) - (t(H) + 2m(H)) = -k + 2$$

And

$$a_i = w_i + \Phi(H') - \Phi(H) = k + (-k + 2) = 2$$

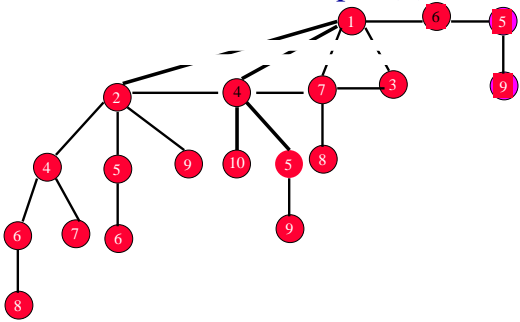
## Deletion of a node $v$

- Perform  $\text{DecreaseKey}(v)$  to value  $-\infty$
- Perform  $\text{ExtractMin}(H)$  – seen next.

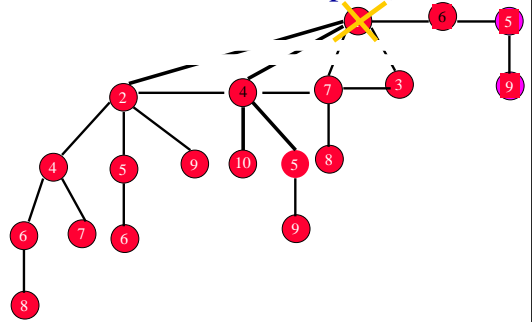
## Extract\_min

- Remember - there is a pointer ( $\text{min}/H$ ) pointing to the min.
- Set  $\text{theNode} = \text{min}/H$
- Moved all children of  $\text{theNode}$  to the roots-list.
  - This is done by merging their sibling list with the root list (constant time)
- Remove  $\text{theNode}$  from its sibling list.
- Free  $\text{theNode}$ .
- Perform  $\text{Consolidate}(H)$  - merging trees.
  - /\* This is a good time to reduce the number of trees \*/

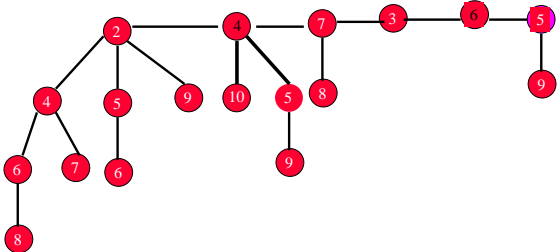
### Extract\_min – example (1)



### Extract\_min – example (1.1)



### Extract\_min – example (2)



Next comes the **consolidation**

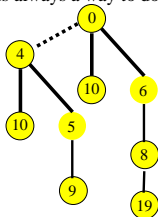
Time analysis for  $\text{Extract\_min}$  operation  
(not including consolidation (counted later) )

- Let  $\text{deg}(v)$  is the number of children of  $v$ .
- **Lemma:** (CLRS 20.3): The number of nodes in a tree the tree rooted at  $v$  is  $\geq \frac{1}{2} \text{deg}(v)$
- **Conclusion 1:**  $\text{deg}(v) = O(\log n)$ , for every node  $v$ .
- The actual time  $w_i$  needed for disconnecting  $v$  from its children and adding them to the roots list –  $O(\log n) = \text{deg}(v)$

## Union of two trees.

### (Need for Consolidation)

- (Similar (but not identical) operation was seen in the binomial heaps)
- **Degree of a tree** is defined as the degree of the root of the tree.
- Given two trees with the same **degree of their roots**, connect the root of one as a child of the other root.
- There is always a way to do so while maintaining the heap order:



The root with larger key becomes the child of the smaller root

Point of potential confusion: For Binomial heaps, trees have the same size iff they have the same degree. Not true here

## Extract\_min – cont: Consolidation.

- Each extract\_min is followed by the **consolidation** operation:
- This operation repeatedly joins trees with same degree, using the tree-union operation:
  - Repeatedly pick two trees with the same degree, and merge them:
    - ...but trees are not sorted by degree, (as oppose to Binomial heaps) and there are many of them – how can this be done efficiently? (on board)
- Finish when no two trees with the same degree exist.
- Recover the new minimum while doing so.
- Actual Time  $w_i$  – proportional to the number of trees
  - (since every operation reduces the number of trees by one, and takes a constant time) .

## Time analysis for consolidation

- The consolidation takes actual time  $t(H)$  time.
- In  $H'$ , there at most one tree for each degree of its root (followed from conclusion 1), so  $t(H') = O(\log n)$ .
- The number of marked nodes is not changed.
- $\Phi(H') - \Phi(H) = (t(H') + 2m(H')) - (t(H) + 2m(H)) = t(H') - t(H) = O(\log n) - t(H)$
- The amortized work is therefore
 
$$t(H) + (O(\log n) - t(H)) = O(\log n)$$

## Time analysis for Delete

- Deletion consists of
  - first DecreaseKey (amortized time  $O(1)$ ) and then
  - ExtractMin (amortized time  $O(\log n)$ )
- Total amortized work:  $O(\log n)$

## Toward proving lemma CLRS 20.3

- **Claim:** Let  $F_0 = F_1 = 1$  and  $F_{k+2} = F_{k+1} + F_k$ . Then (induction)  $F_{k+2} \geq \phi^k$
- **Lemma 20.2:**  $F_{k+2} = 1 + \sum_{i=0}^k F_i$
- **Proof** – by induction, on the board.
- **Lemma 20.1:** Let  $x$  be a root, and let  $y_1, \dots, y_k$  denote its children, in the order they joined  $x$ . Then  $\deg[y_i] \geq i-1$ . ( $i=2, 3, \dots, k$ ).
- **Proof:**
  - When  $y_i$  joined  $x$ , its degree was exactly  $i$ .
  - Since then its degree might have dropped to  $i-1$  (this is where we needed the rule that an internal node might loose at most one child)

## Proving lemma CLRS 20.3

- Let  $s_k$  denote the minimum number of nodes at a tree of degree  $k$ .
- **Lemma 20.3** :  $s_k \geq \phi^k$
- **Proof:** Let  $y_1, \dots, y_k$  denote its children of a node  $x$ , in the order they joined  $x$ .
  - The degree of  $y_i$  is  $\geq i-1$ ,
  - hence containing  $\geq F_{i-1}$  nodes,
  - $s_k = 1$  (root) + sum of number of nodes in subtrees