CSc 553

Principles of Compilation

5: Procedure Calls

Department of Computer Science University of Arizona

correct gaganer.com

Copyright © 2011 Christian Collberg



Introduction

Procedure Calls

- How do we deal with recursion? Every new recursive call should get its own set of local variables.
- How do we pass parameters to a procedure?
 Call-by-Value or Call-by-Reference?
 - Call-by-Value or Call-by-Reference
 In registers or on the stack?
- In registers or on the stace
- How do we allocate/access local and global variables?
- How do we access non-local variables? (A variable is non-local in a procedure P if it is declared in procedure that statically encloses P.)
- How do we pass large structured parameters (arrays and records)?

Run-Time Memory Organization

Low	\Rightarrow	Heap
Addresses		
		1
		Stack
		Static Data
High		Initialized Data
Addresses	\Rightarrow	Text Segment

 The Text Segment holds the code (instructions) of the program. The Initialized Data segment holds strings, etc, that don't change. Static Data holds global variables. The Stack holds procedure activation records and the Heap dynamic data.

Storage Allocation I

Global Variables - MIPS I

We'll examine three ways.

```
Strings (such as "Bart!") are stored in the Initialized
            Data section
Own Variables are stored in the Static Data area. An Own
            variable can only be referenced from within the
            procedure in which it is declared. It retains its value
            between procedure calls.
            PROCEDURE P (X : INTEGER);
               OWN W : INTEGER:
               VAR L : INTEGER:
            BEGIN W := W + X: END P
Dynamic Variables are stored on the Heap:
            PROCEDURE P ();
               VAR. X : POINTER TO CHAR:
            BEGIN NEW(X) END P
```

4 byte boundary.

 Allocate one block of static data (called Data, for example), holding all global variables. Refer to individual variables by

Global Allocation in Block:

Global Variables are stored in the Static Data area.

```
PROGRAM P;
  VAR X : INTEGER; (* 4 bytes. *)
  VAR C : CHAR;
                   (* 1 byte. *)
  VAR R : REAL; (* 4 bytes. *)
END
             __ Global Allocation by Name: _____
```

Allocate each global variable individually in the data section.

variables through the Global Pointer \$gp, which is set to

• How do we allocate space for and access global variables?

Running Example:

Prepend an underscore to each variable to avoid conflict with reserved words Remember that every variable has to be aligned on an address

that is a multiple of its size.

Global Variables - MIPS III

Global Allocation on Stack: · Allocate global variables on the bottom of the stack. Refer to

point to the beginning of the stack.

main: subu \$sp,\$sp,48 move \$gp,\$sp

lw \$2,0(\$gp) 1h

\$3, 4(\$gp) 1.s \$f4, 8(\$gp)

Pros and Cons _X: .space 4 Easy, but slow. Each access lw \$2, _X takes 2

R

offsets from Data data .space 48

Global Variables - MIPS II

.data

_X:

C:

R.:

main:

.space 4

.space 1

.align 2

.space 4

lw \$2, X

.text

_Data:

.text main:

٦ω \$2. _Data+0

Data:

cvcles.

variables

.space 48 Same as above. subu \$sp,\$sp,48 1 cycle to access the first 64K global

10 × 10 × 12 × 12 × 12 × 10 × 10

Storage Allocation II

Storage Allocation III

LocalvVariables: stored on the run-time stack.

Actual parameters: stored on the stack or in special argument registers.

- Languages that allow recursion cannot store local variables in the Static Data section. The reason is that every
 Procedure Activation needs its own set of local variables.
- For every new procedure activation, a new set of local variables is created on the run-time stack. The data stored for a procedure activation is called an Activation Record.
- Each Activation Record (or (Procedure) Call Frame) holds the local variables and actual parameters of a particular procedure activation.

 When a procedure call is made the caller and the callee cooperate to set up the new frame. When the call returns, the frame is removed from the stack.

Recursion Examples

Recursion Example I

n:INTEGER)

Example I (Factorial function):

R₀ and R₁ are registers that hold temporary results.

 We show the status of the stack after the first call to B(1) has completed and the first call to B(0) is almost ready to return.

Example II (Fibonacci function):

 The next step will be to pop B(0)'s AR, return to B(2), and then for B(2) to return with the sum B(1)+B(0).



:INTEGER;
VAR L:INTEGER;
BEGIN
(1) IF n <= 1
(2) THEN L:=1;
(3) ELSE
(4) R₀:=F(n-1);
(5) R₁:=n;
(6) L:=R₀*R₁;
(7) ENDIF;
(8) RETURN L;
END F;
BEGIN

(9)=F(3);

 $\begin{array}{l} n = 1 \\ L = 1 \\ Ret A d d r = (5) \\ Ret V a l = 1 \\ n = 2 \\ L = ? \\ Ret V a l = ? \\ Ret V a l = ? \\ n = 3 \\ L = ? \\ Ret A d d r = (10) \\ Ret V a l = ? \\ C = ? \\ \end{array}$

F(2)

F(3)

main

F(1)

Recursion Example II

```
PROCEDURE B (
 n:INTEGER)
                       n = 1; L = 1
 : INTEGER:
                       RetAddr=(6)
                                              B(0)
 VAR L: INTEGER:
                       RetVal=1
REGIN
(1) IF n <= 1
                       n=2;
                                L=?
     THEN L:=1:
                       R_0 = 1
(2)
                                              B(2)
                      RetAddr=(5)
     FLSE
(3)
                      RetVal=?
     R_0 := B(n-1) :
(4)
     R_1 := B(n-2):
                       n = 3: L = ?
(5)
(6)
      L := R_0 + R_1
                      RetAddr=(5)
                                              B(3)
     ENDIF:
                       RetVal=?
(7)
     RETURN L:
(8)
                       n = 4: L = 9
END B:
                       RetAddr=(10)
                                              B(4)
REGIN
                       RetVal=?
     (9)=B(4):
                       C = ?
                                             main
```

Calling Sequences

Procedure Call Conventions

- Who does what when during a procedure call? Who pushes/pops the activation record? Who saves registers?
- This is determined partially the hardware but also by the conventions imposed by the operating system.
- . Some work is done by the caller (the procedure making the call) some by the callee (the procedure being called).

Work During Call Sequence: ___

· Allocate Activation Record, Set up Control Link and Static Link. Store Return Address. Save registers.

. Work During Return Sequence: ___ · Deallocate Activation Record, Restore saved registers, Return

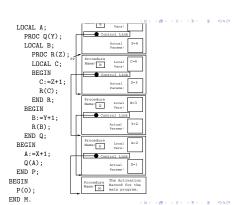
function result Jump to code following the call-site.

Example Call/Return Sequence

The Call Sequence	
The caller:	
 Allocates the activation record, Evaluates actuals, Stores the return address, Adjusts the stack pointer, and Jumps to the start of the callee's code. 	
The callee:	
Saves register values, Initializes local data, Begins execution.	
The Return Sequence	
The callee:	
 Stores the return value, Restores registers, Returns to the code following the call instr. 	
The caller:	

· Restores the stack pointer, Loads the return value.

The Control Link



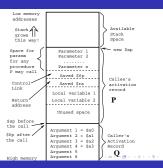
The Control Link I

- Most procedure calling conventions make use of a frame pointer (FP), a register pointing to the (top/bottom/middle of the) current activation record.
- Local variables and actual parameters are accessed relative the FP. The offsets are determined at compile time. MIPS example: 1w \$2, 8(\$fp)
 - Each activation record has a control link (aka dynamic link), a pointer to the previous activation record on the stack. The control link is simply the stored FP of the previous activation.



Procedure Call on the MIPS

MIPS Procedure Call I



- Assume that a procedure Q is calling a procedure P. Q is the caller, P is the callee. P has K parameters.
- Q has an area on it's activation record in which it passes arguments to procedures that it calls. Q puts the first 4 arguments in registers (\$a0-\$a3 ≡ \$4--\$7). The remaining K 4 arguments Q puts in its activation record, at 16+\$sp, 20+\$sp, 24+\$sp etc. (We're assuming that all arguments are 4 bytes long).
- Note that there is space in Q's activation record for the first 4 arguments, we just don't put them in there.
- We must know the max number of parameters of an call Q makes, to know how large to make its activation record.

920 3 (5) (5) (6) (0)

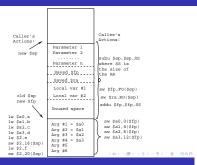
MIPS Procedure Call II

MIPS Procedure Call III

- Next, Q executes a jal (jump and link) instruction. This puts the return address (the address right after the jal instruction) into register \$ra (\$31), and then jumps to the beginning of P.
- Before P starts executing it's code, it has to set up it's stack frame (activation record). How much space does it need?
 - Space for local variables,
 - Space for the control link (old \$fp 4 bytes).
 - Space to save the return address \$ra (4 bytes).
 - Space for parameters P may want to pass when making calls itself.

Furthermore, the size of the activation record must be a multiple of 8! This can all be computed at compile-time.

- Given the size of the stack frame (SS) we can set it up by subtracting from \$sp (remember that the stack grows towards lower addresses!): subu \$sp,\$sp,SS. We also set \$fp to point at the bottom of the stack frame.
- If P makes calls itself, it must save \$a0--\$a3 into their stack locations.
- Procedures that don't make any calls are called leaf routines.
 They don't need to save \$a0--\$a3.
- Procedures that make use of registers that need to be preserved accross calls, must make room for them in the activation record as well.



MIPS Procedure Returns II



- When P wants to return from the call, it has to make sure that everything is restored exactly the way it was before the call.
- P restores \$sp and \$fp to their former values, by reloading the old value of \$fp from the activation record.
- P then reloads the return address into \$ra, and jumps back to the instruction after the call.



(B) (B) (B) (B) (B) (B) (O)

Parameter Passing

Parameter Passing I - Issues

BEGIN P(5 + r. X) END

Call-by-Value Parameters

_ Value Parameters: _	PROG M; $ \begin{array}{c} \text{PROC P(X:INT);} \\ \text{PROC P(X:INT);} \\ \text{BEGIN X:=5 END P;} \\ \hline \text{VAR S:INT;} \\ \text{BEGIN S:=6; P(S); END.} \end{array} $	
callee's activation the actual.	are (usually) copied by the caller into the n record. Changes to a formal won't affect	
PROC P(VAR X:II BEGIN X:=5 END • Reference parame	P; $S=5$ } M eters are passed by passing the address) fo the parameter. Changes to a formal	-00/
I-by-Reference Pa	rameters	
I-by-Reference Pa	Algorithm:	
I-by-Reference Pa		
• The caller compu	Algorithm:	
The caller compuExpression actualThe caller places	Algorithm: attes the arguments' <i>I-value</i> .	
 The caller compu Expression actual The caller places The caller's actual 	Algorithm: tes the arguments' I - v alue. Is (like $a+b$) are stored in a new location. the I - v alues in the c allee's activation record.	

```
Algorithm:
The caller computes the arguments' r-value.
The caller places the r-values in the callee's activation record.
 Consequences:

    The caller's actuals are never affected by the call.

 · Copies may have to be made of large structures.
    Example:
TYPE T = ARRAY 10000 OF CHAR:
PROC P (a:INTEGER: b:T):
BEGIN a:=10; b[5]:="4" END P;
VAR r : INTEGER; X : T;
```

Call-by-Name Parameters I

BEGIN P(r, X) END

- (Un-)popularized by Algol 60.
- A name parameter is (re-)evaluated
 - every time it is referenced.
 - in the callers environment.
 - _____ Algorithm: _____
- 1 The caller passes a thunk, a function which computes the argument's I-value and/or r-value, to the callee.
- The caller also passes a static link to its environment. 3 Every time the callee references the name parameter, the
- thunk is called to evaluate it. The static link is passed to the thunk.

```
Call-by-Name Parameters II
```

Algorithm:

1 If the parameter is used as an I-value, the thunk should return an I-value, otherwise an r-value.

If the parameter is used as an I-value, but the actual parameter has no I-value (it's a constant), the thunk should produce an error. Consequences:

 Every time a callee references a name parameter, it may produce a different result.

BEGIN i := i + 1: x := x + 1:

> END: REGIN

Call-by-Name Parameters III

VAR i : INTEGER: VAR a : ARRAY 2 OF INTEGER:

PROC P (NAME x:INTEGER):

i := 1; a[1] := 1; a[2] := 2; P(a[i]): WRITE a[1], a[2]: FND

Call-by-Name V - Jensen's Device

Call-by-Name Parameters IV

i := i + 1:

```
VAR i : INTEGER:
VAR a : ARRAY 2 OF INTEGER:
PROC P (thunk : PROC()):
```

_____ Implementation: _____

 $thunk()\uparrow := thunk()\uparrow + 1:$

PROC thunk1 () : ADDRESS; BEGIN RETURN ADDR(a[i]) END;

BEGIN

REGIN

END:

i := 1; a[1] := 1; a[2] := 2; P(thunk1);

PROC Sum (NAME Expr : REAL;

VAR i : INTEGER;

NAME Idx : INTEGER; Max : INTEGER) : INTEGER; VAR Result : REAL := 0; BEGIN FOR i := 1 TO Max DO; Idx := i;Result := Result + Expr; ENDFOR: RETURN Result; END:

REGIN WRITE Sum(i, i, 5); $(* \sum_{i=1}^{5} i *)$ WRITE Sum(i*i, i, 10): $(* \sum_{i=1}^{10}, i^2 *)$ Large value parameters have to be treated specially, so that a change to the formal won't affect the actual. Example:

Access to Non-Local Names

```
TYPE T = ARRAY [1..1000] OF CHAR;

PROCEDURE P (x : T);

BEGIN x[5] := "f"; END P;

VAR L : T; BEGIN P(L); END

Algorithm 2: Caller Copy

PROCEDURE P (VAR x : T);

BEGIN x[5] := "f"; END P;

VAR L : T; LT : T;

BEGIN copy(LT, L, 1000); P(LT); END
```

Accessing Non-Local Variables I

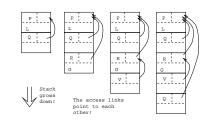
```
PROGRAM M;
  PROC P(n);
  LOCAL L;
    PROC Q();
    BEGIN PRINT L; END Q;
                                n=3; L=3
                                                       P(1)
  BEGIN
    L := n * 3;
                                n=2; L=6
                                                       P(2)
    IF n \ge 1
                                n=3; L=9
      THEN P(n-1);
      ELSE Q();
    ENDIF:
  END P;
BEGIN P(3); END M.
  . Which L should Q print? There are three Ls on the stack to
    choose from!

    Q should print the L from the topmost P on the stack.
```

```
PROCEDURE P (a:INTEGER):
  VAR T. · INTEGER ·
  PROCEDURE Q (x:INTEGER):
  BEGIN R(16) END 0:
  PROCEDURE R (y:INTEGER);
     VAR G · INTEGER ·
     PROCEDURE V (z:INTEGER):
     BEGIN Q(10) END V:
  BEGIN V(12) END R:
```

BEGIN Q (5): END P:

- · We give each activation record an Access Link (aka Static Link).
- Assume that Q is nested within P (as above). Then Q's static



Accessing Non-Local Vars. IV

PROC P (); VAR T.: INTEGER: $\Leftarrow m_L = 1$ PROC R (); $n_{R} - n_{L} = 2$ PROC V (); **BEGIN** L:=...**END** V; $\Leftarrow n_{\text{R}} = 3$

- Assume that L is declared at nesting level n_L, and that the reference to L is at nesting level n_R (as above).
- Follow $n_R n_L$ access links. We now point to the activation record for the most recent activation of P. MIPS Example:

lw \$2, AL(\$fp) # AL is offset of access link.

lw \$2, (\$2) # An access link points to # the previous access link.

lw \$3, 12(\$2) # Get the data in the AR.

Access to non-local variable L:

Setting up Access Links I

record.

- . Every time we make a procedure call we have to set up the access link for the new procedure activation.
- There are two cases to consider: (1) when the callee is nested within the caller, and (2) when the caller is nested within the callee.

- P calls Q. P is at level N_P, Q is at level N_Q. N_P = N_Q − 1,
- since Q must be nested immediately within P. . Make Q's access link point to the access link in P's activation

Setting up Access Links II

Case (2): Caller Within Callee:

PROG M;

PROC Q();

PROC P();

P

- \bullet P calls Q. P is at level $N_{\rm P}$, Q is at level $N_{\rm Q}$. $N_{\rm P} \geq N_{\rm Q}$.
- Traverse the access links to find the most recent activation of the first procedure which statically encloses both P and Q.
- We need to follow $N_P N_Q + 1$ links.

Summary

Summary I Summary II

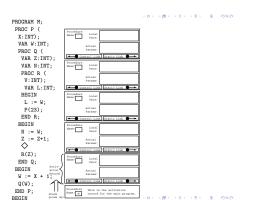
- Read the Dragon Book:
 Procedures 389–394
 Storage Organiz 396–397, 401–404
 Activation Records 398–400
 Calling Sequences 404–408
 Lexical Scope 411, 415–418
 Parameter Passing 424–427
- Each procedure call pushes a new activation record on the run-time stack. The AR contains local variables, actual parameters, a static (access) link, a dynamic (control) link, the return address, saved registers, etc.
- The frame pointer (FP) (which is usually kept in a register) points to a fixed place in the topmost activation record. Each local variable and actual parameter is at a fixed offset from

- The dynamic link is used to restore the FP when a procedure call returns
- The static link is used to access non-local variables, i.e. local variables which are declared within a procedure which statically encloses the current one.
- A parameter is often passed by the caller copying it (or its address, in case of VAR parameters) into the callees activation record. On the MIPS, the caller has an area in its own activation record in which it puts actual parameters before it jumps to the callee. For each procedure P the compiler figures out the maximum number of arguments P passes to any procedure it calls. The corresponding amount of memory has to be allocated in P's activation record.

Exam Problems

Show the status of the run-time stack when execution has reached point of for the second time in the program on the next slide. Fill in the name of each procedure invocation in the correct activation record. Also fill in the values of local variables and actual parameters, and show where the static links and control links are pointing. Assume that all actual parameters are passed on the stack rather than in registers.

40 × 45 × 42 × 42 × 32 × 900



Homework

Homework I

Draw the stack when control reaches point
 of rethe third time. Include all actual parameters, local variables, return addresses, and static and dynamic links.

```
PROGRAM M;

PROCEDURE P(X:INTEGER);

VAR A: INTEGER;

PROCEDURE Q(Y: INTEGER);

VAR B: INTEGER;

BEGIN

B:= Y + 1; A:= B + 2;

P(B);

END Q;

BEGIN

A:= X + 1; Q(A);

FND P:
```