# CSc 553 - Principles of Compilation 

7 : Code Generation I

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Introduction

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## 3 Code Generation Issues I

- The purpose of the code generation phase of the compiler is to transform the intermediate code produced by the front end into some other code that can be executed.
- Often the the code generator will produce assembly code or object code which (after assembly and linking) can be directly executed by the hardware.
- Alternatively, the code generator can generate C-code and use the native C-compiler as the "real" back-end.
- Or, the code generator can generate code for a "virtual machine", and use an interpreter to execute the code.
- We expect the code generator to produce code that is as efficient as possible.


## 4 Code Generation Issues II



## 5 Code Generation Issues III

- The input to the code generator can be any one of the intermediate representations we've discussed: Trees, Tuples, Graphs,...
- The work of the code generator consists of several (interdependent) tasks:


## Instruction

- selection: Which instructions should be generated?
- scheduling: In which order should they be generated?


## Register

- allocation: Which variables should be kept in registers?
- assignment: In which registers should they be stored?
- spilling: Which registers should be spilled when?

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## Architectures

## 7 Machine Architectures I


$\qquad$

```
3-Register: add R1, R2, R3
    [R1 := R2 + R3] (MIPS,VAX, \(\cdot\) ).
Register-Address: add R, Addr
    [ \(\mathrm{R}:=\mathrm{R}+\mathrm{Addr}]\) (VAX,x86,MC68k)
2-Register: add R1, R2
    [R1 : = R1 + R2] (VAX, x86,MC68k)
2-Address: add Addr1, Addr2
    [Addr1 := Addr1 + Addr2] (VAX)
    [Addr1 := Addr2 + Addr3] (VAX)
```

Kinds of Register Classes: $\qquad$
General One set of register that can hold any type of data (VAX, Alpha).
Integer+Float Separate integer and floating point register sets (Sparc, MIPS).

## 8 Machine Architectures II

$\qquad$
$\qquad$
Integer+Float+Address Separate integer, floating point, and address register sets (MC68k).
$\qquad$
$\qquad$
Immediate: \#X The value of the constant X. (All architectures.)
Register Direct: $R$ The contents of register R. (All architectures.)
Register Indirect: (R) The contents of the memory address in register R. (All.)
Register Indirect with increment: $(R+)$ The contents of the memory address in register $R$. $R$ is incremented by the size of the instruction (i.e. if MOVE. W ( $\mathrm{R}+$ ), Addr moves two bytes, then R would be incremented by 2). (VAX, MC68k.)

## 9 Machine Architectures III

Kinds of Addressing Modes: $\qquad$
Register Ind. with Displacement: $d(R)$ The contents of the memory address $R+d$, where $R$ is a register and da (small) constant. (All architectures.)

The Cost of an instruction: $\qquad$

- The Cost of an instruction is the number of machine cycles it takes to execute it.
- On RISCs, most instructions take 1 cycle to execute. Loads, stores, branches, multiplies, and divides may take longer.
- On CISCs, the number of cycles required to execute an instruction $\operatorname{Instr} 0 p_{1}, O p_{2}$ is cost (Instr) $+\operatorname{cost}\left(0 p_{1}\right)+\operatorname{cost}(1$ $\operatorname{cost}\left(0 p_{i}\right)$ is the number of cycles required to compute the addressing mode $0 \mathrm{p}_{i}$.

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## A Simple Example

## 11 Code Generation Example I

- A straight-forward code generator considers one tuple at a time, without looking at other tuples. The code generator is simple, but the generated code is sub-optimal.
int $A[5]$, i, $x$;
$\operatorname{main}()\{$ for $(i=1 ; i<=5 ; i++) x=x * A[i]+A[i] ;\}$
The Tuple Code

| (1) $\mathrm{i}:=1$ | (9) $\mathrm{T} 5:=\mathrm{i}$ |
| :--- | :--- | :--- |
| (2) T0 $:=\mathrm{i}$ | (10) $\mathrm{T} 6:=\mathrm{A}[\mathrm{T} 5]$ |
| (3) IF T0<6 GOTO (5) | (11) $\mathrm{T} 7:=\mathrm{T} 4+\mathrm{T} 6$ |
| (4) GOTO (17) | (12) $\mathrm{x}:=\mathrm{T} 7$ |
| (5) T1 $:=\mathrm{i}$ | (13) T8 $:=\mathrm{i}$ |
| (6) T2 $:=\mathrm{A}[\mathrm{T} 1]$ | (14) $\mathrm{T} 9:=\mathrm{T} 8+1$ |
| (7) T3 $:=\mathrm{x}$ | (15) $\mathrm{i}:=\mathrm{T9}$ |
| (8) T4 $:=\mathrm{T} 2 * \mathrm{~T} 3$ | (16) GOTO (2) |

## 12 Code Generation Example II (A)

$\qquad$ Unoptimized MIPS Code: $\qquad$

|  | $(1) \mathrm{i}:=1$  <br> li  <br> \$2,0x1 \# \$2 $:=1$ <br> sw $\$ 2, \mathrm{i}$ | $\#$ i $:=\$ 2$ |
| :--- | :--- | :--- |

L2: $\begin{array}{ll}\text { (2) T0 }:=\mathrm{i} \\ \text { lw } & \\ \$ 2, \mathrm{i} & :=\end{array}$
slt $\begin{aligned} & \text { (3) IF i < } 6 \text { GOTO (5) } \\ & \$ 3, \$ 2,6 \quad \# \text { \$3 }:=\text { i }<6\end{aligned}$
bne \$3,\$0,L5 \# IF \$3 $=0$ GOTO L5
(4) GOTO (17)
j L3 \# GOTO L3
L5: $\begin{aligned} & \text { (5) T1 }:=\mathrm{i} \\ & \text { lw } \\ & \$ 2, \mathrm{i}\end{aligned}$

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|  | (6) $\mathrm{T} 2:=\mathrm{A}$ [ | 1] |
| :---: | :---: | :---: |
| move | \$3,\$2 \# | \$3 : = \$2 |
| sll | \$2,\$3,2 \# | \$2 : $=$ \$3*4 |
| la | \$3, A \# | \$3 := ADDR(A) |
| addu | \$2,\$2,\$3 \# | \$2 := \$2 + \$3 |
| 1w | \$2,0(\$2) \# | \$2 : $=\operatorname{CONT}(\mathrm{A}[\mathrm{i}])$ |
|  | (7) T3 := x |  |


| 1w | \$3, x \# \$3 : $=\operatorname{CoNT}(\mathrm{x})$; |
| :---: | :---: |
|  | (8) T4 := T2 * T3 |
| mult | \$3,\$2 \# \$10 : = \$3 * \$2 |
| mflo | \$4 \# \$4 := \$10 |
|  | (9) T5 : $=\mathrm{i}$ |
| 1w | \$2,i \# \$2 : = CONT (i) |
|  | (10) T6 := A [T5] |
| move | \$3,\$2 \# \$3 := \$2 |
| sll | \$2,\$3,2 \# \$2 := \$3*4 |
| la | \$3,A \# \$3 := ADDR(A) |
| addu | \$2,\$2,\$3 \# \$2 := \$2 + \$3 |
| lw | \$3,0(\$2) \# \$2 := CONT (A[i] |

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du

| $(11) \mathrm{T} 7:=\mathrm{T} 4+\mathrm{T} 6$ |
| :--- |
| $\$ 2, \$ 4, \$ 3 \quad \# \quad \$ 2:=\$ 4+\$ 3$ |

(12) $\mathrm{x}:=\mathrm{T} 7$
sw \$2,x \# x := \$2

$\begin{array}{ll}(14) \mathrm{T} 9 & :=\mathrm{T} 8+1 \\ \$ 2, \$ 3,1 \quad \# & \$ 2\end{array}$
move $\$ 3, \$ 2$ \# \$3 := \$2
(15) i := T9
sw \$3,i \# i := \$3
(16) GOTO (2)
j L2 \# GOTO L2
L3:

## 15 Code Generation Example III (A)

- The generated code becomes a lot faster if we perform Common Sub-Expression Elimination (CSE) and keep the index variable i in a register (\$6) over the entire loop:

$$
\begin{array}{|l|}
\hline(1) \mathrm{i}:=1 \\
\$ 6,0 \times 1
\end{array} \text { \# \$6 }:=1
$$

L2:
slt \$3,\$6,6 \# \$3 := i < 6
bne $\$ 3, \$ 0, \mathrm{~L} 5 \quad \#$ IF $\$ 3 \neq 0$ GOTO L5
(4) GOTO (17)
j L3 \# GOTO L3

L5:
(5) $\mathrm{T} 1:=\mathrm{i}$

## 16

- A[T1] is computed once, and the result is kept in register $\$ 5$ until it's needed the next time.

|  | (6) $\mathrm{T} 2:=\mathrm{A}[\mathrm{T} 1]$ |
| :---: | :---: |
| move | \$3,\$6 \# \$3 := \$6 |
| sll | \$2,\$3,2 \# \$2 := \$3*4 |
| la | \$3,A \# \$3 : $=\operatorname{ADDR}(\mathrm{A})$ |
| addu | \$2,\$2,\$3 \# \$2 := \$2 + \$3 |
| 1w | \$5,0(\$2) \# \$5 := CONT(A[i]) |
|  | (7) T3 : $=\mathrm{x}$ |
| 1w | \$3, x \# \$3 := $\operatorname{CONT}(\mathrm{x})$; |
|  | (8) T4 := T2 * T3 |
| mult | \$3,\$5 \# \$10 := \$3 * \$5 |
| mflo | \$4 \# \$4 := \$10 |
|  | (9) $\mathrm{T} 5:=\mathrm{i}$ |
|  | (10) T6 := A [T5] |

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- After the loop we need to store the value of $\$ 6$ which has been used to hold the loop index variable i.


|  | (13) $\mathrm{T} 8:=\mathrm{i}$ |  |  |
| :---: | :---: | :---: | :---: |
|  | (14) T9 : $=\mathrm{T} 8+1$ |  |  |
|  | (15) i := T9 |  |  |
| addu | \$6,\$6,1 | \$6 |  |


|  | (16) GOTO (2)  <br>   <br> j L2 <br> L3: sw \$6,i | \# i $:=$ \$6 |
| :---: | :--- | :--- | :--- |

## 18 Code Generation Example IV (A)

- Since x and $\operatorname{ADDR}(\mathrm{A})$ seem to be used a lot in the loop, we keep them in registers ( $\$ 7$ and $\$ 8$, respectively) as well.
- We also reverse the comparison, which allows us to remove one jump.
- The move instruction is unnecessary, so we remove it also.

```
        (1) i := 1
    li $6,0x1 # $6 := 1
    lw $7,x # $7 := CONT(x);
    la $8,A # $8 := ADDR(A)
L2:
    sge ## (4)GOTO (17)
    bne $3,$0,L3 # IF $3}=0\mathrm{ GOTO L3
```

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L5:

|  | (5) T1 : $=\mathrm{i}$ |
| :---: | :---: |
|  | (6) T2 := A[T1] |
| sll | \$2,\$6,2 \# \$2 := \$3 * 4 |
| addu | \$2,\$2,\$8 \# \$2 := \$2 + \$8 |
| 1w | \$5,0(\$2) \# \$5 := $\operatorname{CONT}(\mathrm{A}[\mathrm{i}])$ |
|  | (7) T3 : $=\mathrm{x}$ |
|  | (8) T4 $:=\mathrm{T} 2 * \mathrm{~T} 3$ |
| 1 t | \$7,\$5 \$ \$10 := \$7* \$5 |
| mflo | \$4 \# \$4 := \$10 |


| (9) $\mathrm{T} 5:=\mathrm{i}$ |
| :--- |
| (10) $\mathrm{T} 6:=\mathrm{A}[\mathrm{T} 5]$ |
| (11) $\mathrm{T} 7:=\mathrm{T} 4+\mathrm{T} 6$ |
| (12) $\mathrm{x}:=\mathrm{T} 7$ |
| $\$ 7, \$ 4, \$ 5 \quad \# \quad \$ 7:=\$ 4+\$ 5$ |

$$
\begin{array}{|l|}
\hline \text { (13) } \mathrm{T} 8:=\mathrm{i} \\
\hline \text { (14) } \mathrm{T} 9:=\mathrm{T} 8+1 \\
\hline
\end{array}
$$

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- The unoptimized code (produced by gcc -S -g) was 28 instructions long. Our optimized code is 16 instructions. Improvement: $42 \%$.
- More importantly, in the original code there were 26 instructions inside the loop, and 2 outside. Since the loop runs 5 times, we will execute $3+5 * 25=128$ instructions.
- In the optimized case, we have 11 instructions in the loop and 5 outside. We will execute only $5+5 * 11=60$ instructions. Improvement: $53 \%$.


## Instruction Seleection

## 22 Instruction Selection I

- Instruction selection is usually pretty simple on RISC architectures - there is often just one possible sequence of instructions to perform a particular kind of computation.
- CISC's like the VAX, on the other hand, leave the compiler with more choices: ADD2 1, R1 ADD3 R1, 1, R1 INC R1 all add 1 to register R1.

| set | V , \% 00 | \# \% ○0 : $=\operatorname{ADDR}(\mathrm{V})$; |
| :---: | :---: | :---: |
| ld | [\%o0], \%o0 | \# \%o0 := CONT(V); |
| set | 2, \%o1 | \# \%o1 := 2; |
| call | .mul, 2 | \# \% ○0 := \% ○0 * \% ○1; |
| nop |  | \# Empty delay slot |

## 23 Instruction Selection II

$$
V * 2 \text { - Better Instr. Selection }
$$

$\qquad$

- The Sparc has a library function .mul and a hardware multiply instruction smul:

```
set V, %o0
ld [%o0], %o0
smul %o0, 1, %०0 # %o0 := %o0 * %o1;
```

$V * 2-$ Even Better Instr. Selection $\qquad$

- The Sparc also has hardware shift instructions (sll, srl).
- Integer multiplication by $2^{i}$ can be implemented as a shift $i$ steps to the left.

```
set V, %o0
ld [%o0], %०0
sll %o0, 1, %०0 # % ○0 := % ○0 * 2;
```


## 24 Instruction Scheduling I

| ld | [\%०0], \% 00 | \# \% o : $=$ CONT (V) ; |
| :---: | :---: | :---: |
| set | 2, \%o1 | \# \%o1 := 2; |
| call | .mul, 2 | \# \% ○ $:=\%$ \% $*$ \% 1 ; |
| nop |  | \# Empty delay slot |

- Instruction scheduling is important for architectures with several functional units, pipelines, delay slots. I.e. most modern architectures.
- The Sparc (and other RISCs) have branch delay slots. These are instructions (textually immediately following the branch) that are "executed for free" during the branch.

```
ld [%o0], %o0 # %o0 := CONT(V);
call .mul, 2
set 2, %o1 # Filled delay slot
```


## 25 Instruction Scheduling II (A)

- The Sparc's integer and floating point units can execute in parallel. Integer and floating point instructions should therefore be reordered so that operations are interleaved.
- Consider this example program:

```
int a, b, c; double x, y, z;
{ a = b - c; c = a + b; b = a + c;
    y = x * x; z = x + y; x = y / z;}
```

- How will the generated code be different if the compiler takes advantage of parallel execution, or not?


## 26 Instruction Scheduling II (B)

```
int a, b, c; double x, y, z;
{ a = b - c; c = a + b; b = a + c;
    y = x * x; z = x + y; x = y / z;}
\begin{tabular}{|c|c|c|c|}
\hline & cc -02 & & cc -03 \\
\hline set & b,\%o3 & fmuld & \%f30,\%f30,\%f28 \\
\hline sub & \% \(00 \%\) \%1,\% 1 & set & c, \% 01 \\
\hline set & a,\%o0 & ld & [\%o1], \%o2 \\
\hline add & \%०4,\%०5,\%०4 & faddd & \%f30, \%f28, \%f30 \\
\hline add & \%o0, \%o2, \% ○0 & set & b, \%o0 \\
\hline set & \(\mathrm{x}, \% 00\) & ld & [\%०0], \% ० 4 \\
\hline fmuld & \%f0, \%f2, \%f0 & set & \(\mathrm{z}, \% \mathrm{~g} 1\) \\
\hline sethi & \%hi (z) , \%o2 & sub & \%०4,\%o2,\%o2 \\
\hline faddd & \%f6,\%f8,\%f6 & fdivd & \%f28, \%f 30 , \%f2 \\
\hline fdivd & \%f \(12, \%\) f \(14, \%\) f 12 & add & \%०4,\%o2,\%०4 \\
\hline & & add & \%०2,\%०4,\%०5 \\
\hline
\end{tabular}
```

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## Register Allocation/Assignment/Spilling

## 28 Register Allocation Issues

Why do we need registers? $\qquad$

1. We only need $4-7$ bits to access a register, but $32-64$ bits to access a memory word.
2. Hence, a one-word instruction can reference 3 registers but a two-word instruction is necessary to reference a memory word.
3. Registers have short access time.

Register Uses:

1. Instructions take operands in regs.
2. Intermediate results are stored in regs.
3. Procedure arguments are passed in regs.
4. Loads and Stores are expensive $\Rightarrow$ keep variables in regs for as long as possible.
5. Common sub-expressions are stored in regs.

## 29 Register Allocation/Assignment

Register Allocation: $\qquad$

- First we have to decide which variables should reside in registers at which point in the program.
- Variables that are used frequently should be favored.

Register Assignment: $\qquad$

- Secondly, we have to decide which physical registers should hold each of these variables.
- Some architectures have several different register classes, groups of registers that can only hold one type of data:
- MIPS \& Sparc have floating point and integer registers;
- MC68k has address, integer, and floating point, etc.


## 30 Register Assignment (A)

- Some architectures pass procedure arguments in registers. If a value is used twice, first in a computation and then in a procedure call, we should allocate the value to the appropriate procedure argument register.
- Sparc passes it's first 6 arguments in registers $\% \circ 0, \% \circ 1, \% \circ 2, \% \circ 3, \% \circ 4, \% \circ 5$.
- See the next slide for an example.


## 31 Register Assignment (B)

```
main () {
    int a,b;
    a = b + 15; / /*\Leftarrow b is used here /*
    P(b); /* \Leftarrow and here. */
}
            \Downarrow \Downarrow}
ld [%fp-8],%o0 # %o0 := CONT(b);
add %o0,15,%o1 # %o1 := %o0 + 15
st %o1,[%fp-4] # a := %o1;
call P,1 # P(%o0)
```


## 32 Register Spilling I

- We may have $8|16| 32$ regs available.
- When we run out of registers (during code generation) we need to pick a register to spill. I.e. in order to free the register for it's new use, it's current value first has to be stored in memory.
- Which register should be spilt? Least resently used, Least frequently used, Most distant use, ... (take your pick).


## Example:

- Assume a machine with registers R1--R3.
- R1 holds variable a; R2 holds b, R3 holds c, and R4 holds d. Generate code for:

```
x = a + b; # & Which reg for x?
y = x + c;
```

- Which register should be spilt to free a register to hold x ?

```
33 Register Allocation Example
FOR i := 1 TO n DO
    B[5,i] := b * b * b;
    FOR j := 1 TO n DO
        FOR k := 1 TO n DO
            A[i,j] := A[i,k] * A[k,j];
        END
    END
END
```

2 Registers Available - k and $\operatorname{ADDR}(\mathrm{A})$ in registers. (Prefer variables in inner loops).
4 Registers Available - k, $\operatorname{ADDR}(A), j$, and i in registers. (Prefer index variables).
5 Registers Available - k, $\operatorname{ADDR}(A), j$, i, and b in registers. (Prefer most frequently used vari-
ables).

## 34 Register Spilling Example

FOR i := 1 TO 100000 DO
A[5,i] := b;
FOR j := 1 TO 100000 DO
A[j,i] := <Complicated Expression>;
END
END
$\qquad$ 1st Attempt (4 Regs available): $\qquad$
Allocation/Assignment: i in $R_{1}, \mathrm{j}$ in $R_{2}, \operatorname{ADDR}(\mathrm{~A})$ in $R_{3}, \operatorname{ADDR}\left(\mathrm{~A}\left[5, \mathrm{l}\right.\right.$ ) in $R_{4}$.
Spilling: Spill $R_{4}$ in the inner loop to get enough registers to evaluate the complicated expression.
$\qquad$
$\qquad$
Allocation/Assignment: i in $R_{1}, \mathrm{j}$ in $R_{2}$, $\operatorname{ADDR}(\mathrm{A})$ in $R_{3}$.
Spilling: No spills. But $\operatorname{ADDR}(\mathrm{A}[5, \mathrm{i}])$ must be loaded every time in the outer loop.

## Basic Blocks and Flow Graphs

## 36 Basic Blocks and Flow Graphs I

- We divide the intermediate code of each procedure into basic blocks. A basic block is a piece of straight line code, i.e. there are no jumps in or out of the middle of a block.
- The basic blocks within one procedure are organized as a flow graph.
- A flowgraph has
- basic blocks $B_{1} \cdots B_{n}$ as nodes,
- a directed edge $B_{1} \rightarrow B_{2}$ if control can flow from $B_{1}$ to $B_{2}$.
- Code generation can be performed on a small or large piece of the flow graph at a time (small=easy, large=hard):

Local Within one basic block.
Global Within one procedure.
Inter-procedural Within one program.
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$\qquad$

```
X := 20; WHILE X < 10 DO
    X := X-1; A [X] := 10;
    IF X = 4 THEN X := X - 2; ENDIF;
ENDDO; Y := X + 5;
```

| (1) $X:=20$ | (5) if $X<>4$ goto (7) |
| :--- | :--- |
| (2) if $X>=10$ goto (8) | (6) $X:=X-2$ |
| (3) $X:=X-1$ | (7) goto (2) |
| (4) $A[X]:=10$ | (8) $Y:=X+5$ |

Flow Graph:


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## Constructing Basic Blocks

## 40 Basic Blocks I

- How do we identify the basic blocks and build the flow graph?
- Assume that the input to the code generator is a list of tuples. How do we find the beginning and end of each basic block?

Algorithm: $\qquad$

1. First determine a set of leaders, the first tuple of basic blocks:
(a) The first tuple is a leader.
(b) Tuple L is a leader if there is a tuple if . . goto L or goto L.
(c) Tuple L is a leader if it immediately follows a tuple if . . goto L or goto L.
2. A basic block consists of a leader and all the following tuples until the next leader.

## 41 Basic Blocks II

```
P := 0; I := 1;
REPEAT
    P := P + I;
    IF P > 60 THEN P := 0; I := 5 ENDIF;
    I := I * 2 + 1;
UNTIL I > 20;
K := P * 3
```

| (1) | $\mathrm{P}:=0$ | $\Leftarrow$ Leader (Rule 1.a) |
| :---: | :---: | :---: |
| (2) | I $:=1$ |  |
| (3) | P : $=$ P + I | $\Leftarrow$ Leader (Rule 1.b) |
| (4) | IF P <= 60 GOTO | (7) |
| (5) | $\mathrm{P}:=0$ | $\Leftarrow$ Leader (Rule 1.c) |
| (6) | I $:=5$ |  |
| (7) | T1 := I * 2 | $\Leftarrow$ Leader (Rule 1.b) |
| (8) | $\mathrm{I}:=\mathrm{T} 1+1$ |  |
| (9) | IF I <= 20 GOTO | (3) |
| (10) | $\mathrm{K}:=\mathrm{P} * 3$ | $\Leftarrow$ Leader (Rule 1.c) |

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Block $B_{1}$ : [(1) P:=0; (2) I:=1]
Block $B_{2}$ : [(3) P:=P+I;
(4) IF $\mathrm{P}<=60 \mathrm{GOTO} B_{4}$

Block $B_{3}$ : [(5) P:=0; (6) I:=5]
Block $B_{4}$ : [(7) T1:=I*2; (8) I:=T1+1;
(9) IF $\mathrm{I}<=20$ GOTO $B_{2}$

Block $B_{5}$ : [(10) K:=P*3]


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## Summary

## 44 Readings and References

- Read the Tiger book:

Instruction selection pp. 205-216
Taming conditional branches pp. 185-188

- Or, read the Dragon book:

Introduction 513-521
Basic Blocks 528-530
Flow Graphs 532-534

## 45 Summary I

- Instruction selection picks which instruction to use, instruction scheduling picks the ordering of instructions.
- Register allocation picks which variables to keep in registers, register assignment picks the actual register in which a particular variable should be stored.
- We prefer to keep index variables and variables used in inner loops in registers.
- When we run out of registers, we have to pick a register to spill, i.e. to store back into memory. We avoid inserting spill code in inner loops.


## 46 Summary II

- Code generation checklist:

1. Is the code correct?
2. Are values kept in registers for as long as possible?
3. Is the cheapest register always chosen for spilling?
4. Are values in inner loops allocated to registers?

- A basic block is a straight-line piece of code, with no jumps in or out except at the beginning and end.
- Local code generation considers one basic block at a time, global one procedure, and inter-procedural one program.

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## Homework

## 48 Homework I

- Translate the program below into quadruples.
- Identify beginnings and ends of basic blocks.
- Build the control flow graph.

```
PROGRAM P;
VAR X : INTEGER; Y : REAL;
BEGIN
    X := 1; Y := 5.5;
    WHILE X < 10 DO
        Y := Y + FLOAT(X);
        X := X + 1;
```

```
        IF Y > 10 THEN
                Y := Y * 2.2;
        ENDIF;
    ENDDO;
END.
```


## 49 07.330 Exam Question - Draw the CFG!

```
int A[5],x,i,n;
(1) i := 1
for (i=1; i<=n; i++) {
    if (i<n) {
        x = A[i];
    } else {
        while (x>4) {
            x = x*2+A[i];
        };
    };
    x = x+5;
}
(2) IF i>n GOTO (14)
(3) IF i>=n GOTO (6)
(4) x := A[i]
(5) GOTO (11)
(6) IF \(\mathrm{x}<=4\) GOTO (11)
(7) \(\mathrm{T} 1:=\mathrm{x} * 2\)
(8) \(\mathrm{T} 2:=\mathrm{A}[\mathrm{i}]\)
(9) \(\mathrm{x}:=\mathrm{T} 1+\mathrm{T} 2\)
(10) GOTO (6)
(11) \(x:=x+5\)
(12) i \(:=i+1\)
(13) GOTO (2)
```

